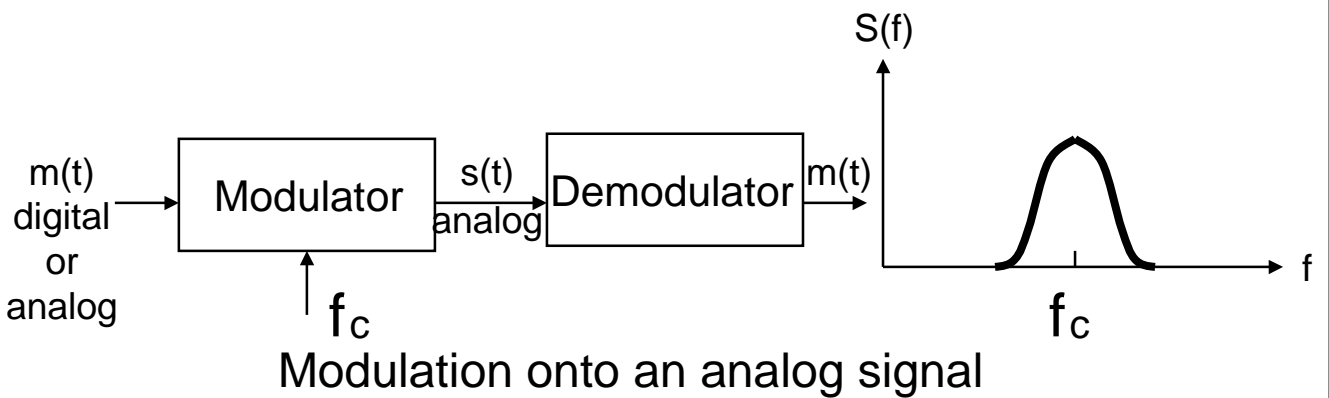
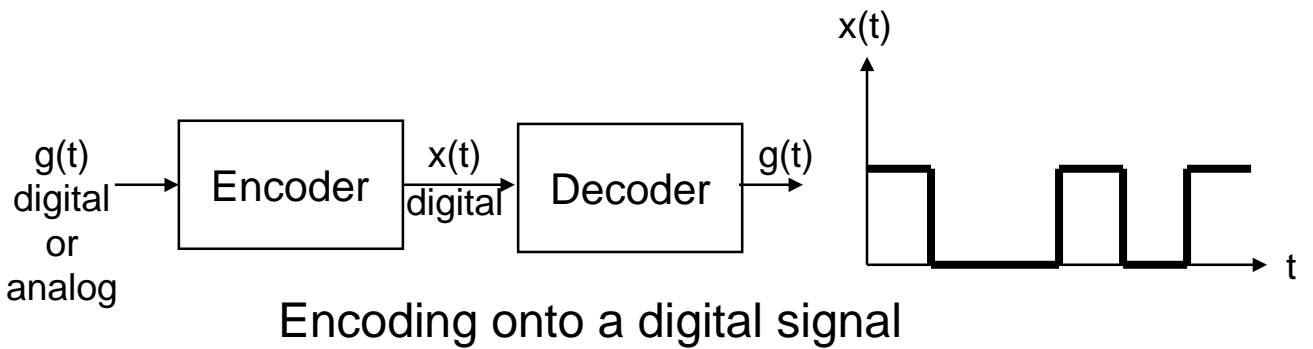


### Encoding and modulation techniques



$m(t)$  = baseband signal or modulating signal       $f_c$  = carrier signal       $s(t)$  = modulated signal

# 1. Digital Data $\Rightarrow$ Digital Signals

- A **digital signal** is a sequence of discrete, discontinuous voltage pulses. Each pulse is a **signal element**
- Binary data are transmitted by encoding each data bit into signal elements
- Encoding scheme: Mapping from data bits to signal elements
- Key data transmission terms

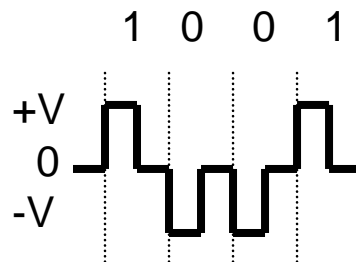
Term	Units	Definition
Data element	bits	A single binary one or zero.
Data rate	bits per second (bps)	The rate at which data elements are transmitted.
Signal element	Digital: a voltage pulse of constant amplitude. Analog: a pulse of constant frequency, phase, and amplitude.	That part of a signal that occupies the shortest interval of a signaling code.
Signaling rate or modulation rate	Signal elements per second (baud)	The rate at which signal elements are transmitted

- Mark: binary digit 1; Space: binary digit 0

- Various encoding schemes
- Evaluation factors
  - Signal spectrum: less bandwidth, no dc component, shape of spectrum (better to center in the middle of bandwidth)
  - Clocking: self-clocking capability is desired for synchronization
  - Error detection: better to have error-detection capability
  - Signal interference and noise immunity:
  - Cost and complexity:

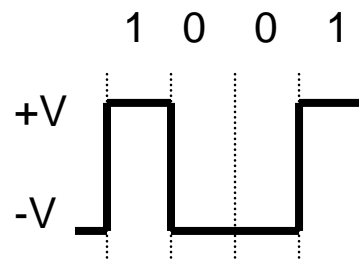
- RZ (Return to Zero)

- 0: positive pulse
- 1: negative pulse
- Signal returns to zero after each encoded bit



- NRZ (Nonreturn to Zero)

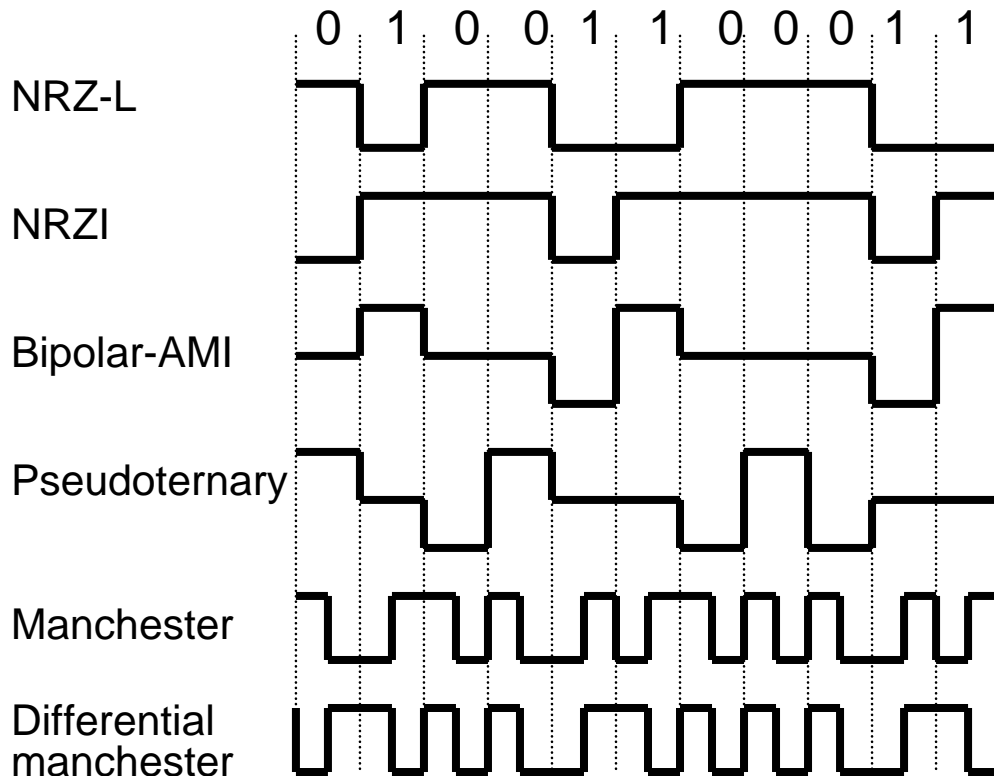
- Voltage level is constant during bit interval (no return to a zero voltage level)
- NRZ-L (NRZ Level)
  - 0: positive voltage
  - 1: negative voltage
- NRZ-I (NRZ Inverted)
  - a form of differential encoding
  - 1: transition at the beginning of bit interval
  - 0: no transition



- NRZ is simple, and efficiently use bandwidth
- NRZ limitations
  - presence of dc component
  - lack of synchronization capability
- Multilevel Binary
  - Bipolar-AMI (Alternate Mark Inversion)
    - Three voltage levels (positive, zero, negative)
    - 0: zero voltage
    - 1: alternately by positive and negative voltages
    - Better synchronization than NRZ
    - no dc component
    - error detection capability
  - Pseudoternary
    - Same as bipolar-AMI, except representation of 0 and 1 is interchanged
- Biphase
  - Always a transition at the middle of each bit interval
  - Manchester
    - 0: high to low transition
    - 1: low to high transition
  - Differential Manchester
    - 0: transition at the beginning of bit interval
    - 1: no transition
  - Synchronization and error detection capability, and no dc component

## Definition of digital signal encoding formats

- Nonreturn-to-Zero-Level (NRZ-L):** 0 = high level, 1 = low level
- Nonreturn-to-Zero Inverted (NRZI):** 0 = no transition at beginning of interval (one bit time), 1 = transition at beginning of interval
- Bipolar-AMI:** 0 = no line signal, 1 = positive or negative level, alternating for successive ones
- Pseudoternary:** 0 = positive or negative level, alternating for successive zeros, 1 = no line signal
- Manchester:** 0 = transition from high to low in middle of interval  
1 = transition from low to high in middle of interval
- Differential Manchester:** Always a transition in middle of interval  
0 = transition at beginning of interval  
1 = no transition at beginning of interval
- B8ZS:** Same as bipolar AMI, except that any string of eight zeros is replaced by a string with two code violations
- HDB3:** Same as bipolar AMI, except that any string of four zeros is replaced by a string with one code violation



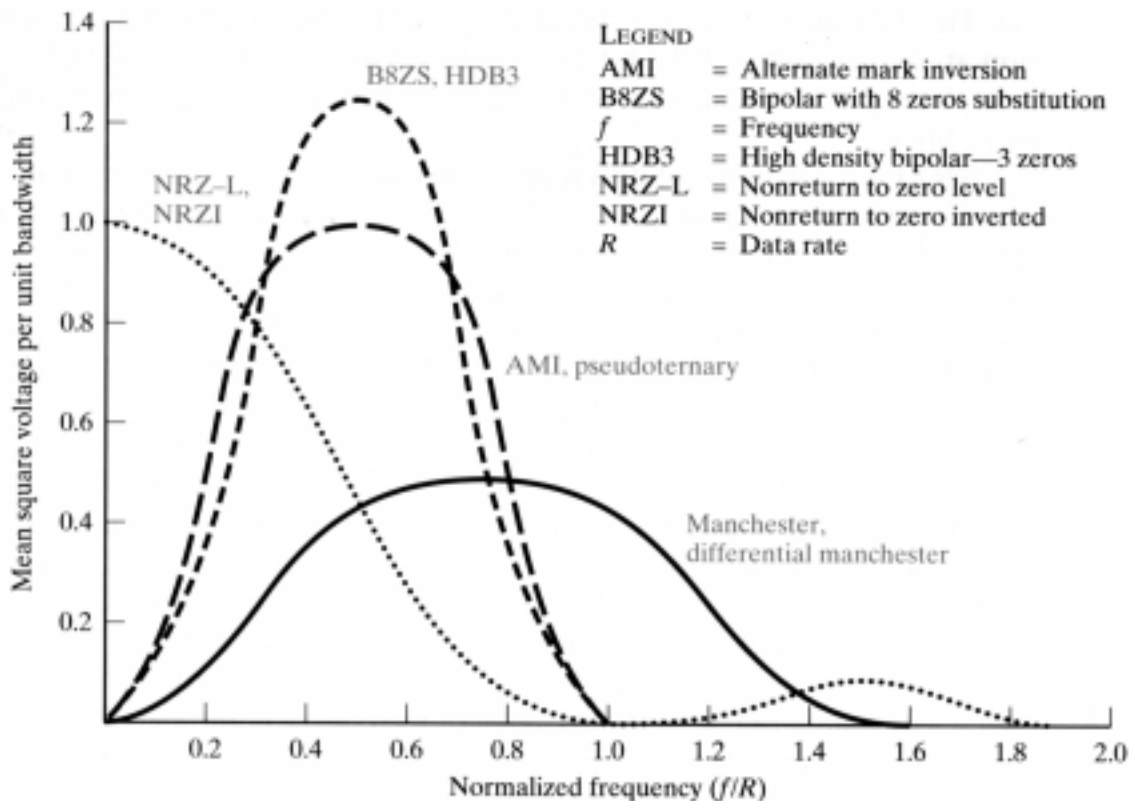
• Modulation Rate

- Data rate (expressed in bps) = modulation rate (or signaling rate or signal transition rate)(expressed in baud) times the number of bits per signal element

**Normalized signal transition rate of various encoding schemes**

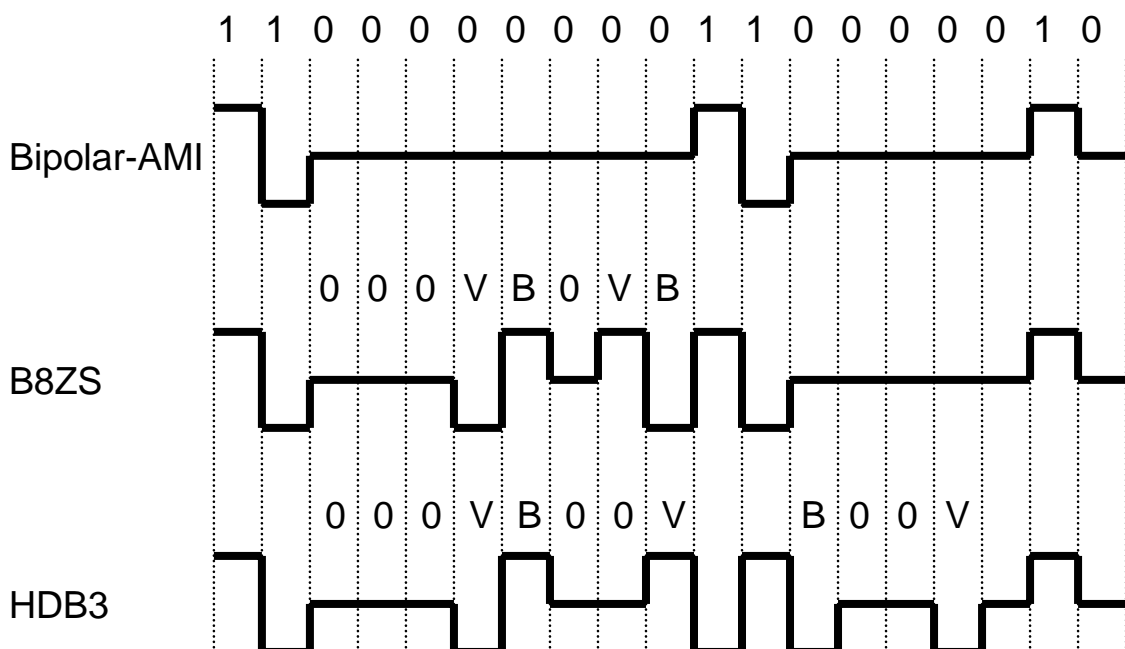
	Minimum	101010...	Maximum
NRZ-L	0 (all 0's or 1's)	1.0	1.0
NRZI	0 (all 0's)	0.5	1.0 (all 1's)
Binary-AMI	0 (all 0's)	1.0	1.0
Pseudoternary	0 (all 1's)	1.0	1.0
Manchester	1.0 (1010...)	1.0	2.0 (all 0's or 1's)
Diff Manchester	1.0 (all 1's)	1.5	2.0 (all 0's)

**Spectral density of various signal encoding schemes**



• Scrambling Techniques

- For long-distance communications
- No dc component, good synchronization and error detection capability, without reduction in data rate
- B8ZS (Bipolar with 8-Zeros Substitution)
  - Based on bipolar-AMI
  - 8 consecutive zeros are encoded as either **000<sub>-</sub>0<sub>-</sub>+** or **000<sub>-</sub>+0<sub>-</sub>**, s.t. two code violations always occur
- HDB3 (High-Density Bipolar 3-Zeros)
  - 4 zeros are encoded as either **000<sub>-</sub>**, **000<sub>+</sub>**, **+00<sub>+</sub>**, or **-00<sub>-</sub>**
  - Substitution rule is s.t. the 4th bit is always a code violation, and successive violations are of alternate polarity (not to introduce dc component)



B = Valid bipolar signal, V = Bipolar violation

## Summary

	NRZ (NRZ-L, NRZI*)	Multilevel Binary (Bipolar AMI, Pseudo ternary)	Biphase (Manchester, Diff. Man.*)	Scrambling (B8ZS, HDB3)
dc Comp.?	Yes	No	No	No
BW Required	B	B	2B	B
Self-clocking?	No	Yes, but ①	Yes	Better than multilevel
Error-detection?	No	Yes	Yes	Yes
Application	-Simple -Digital mag. recording		LAN	Long dist. comm.

\* Differential encoding

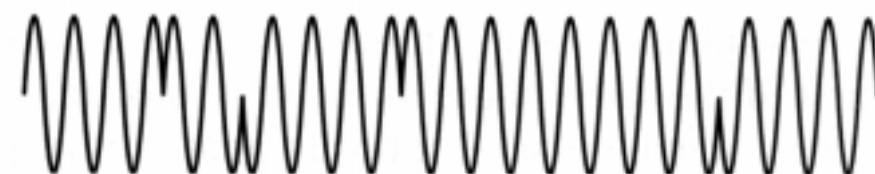
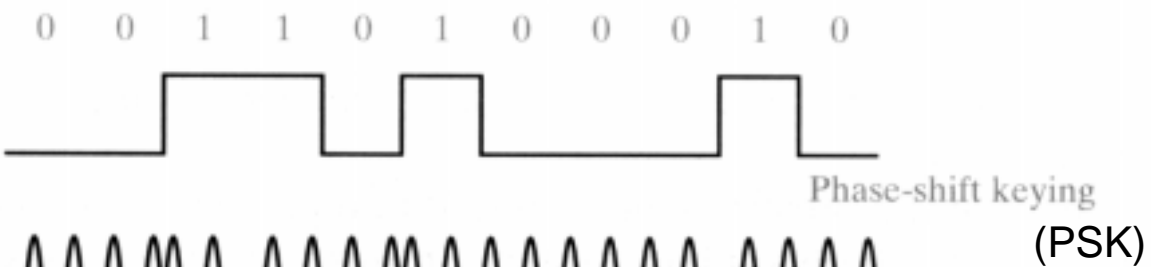
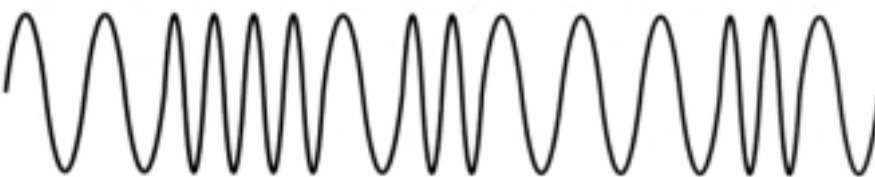
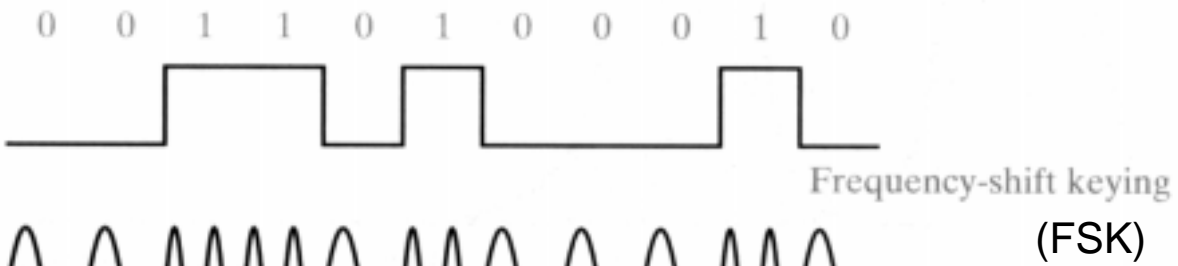
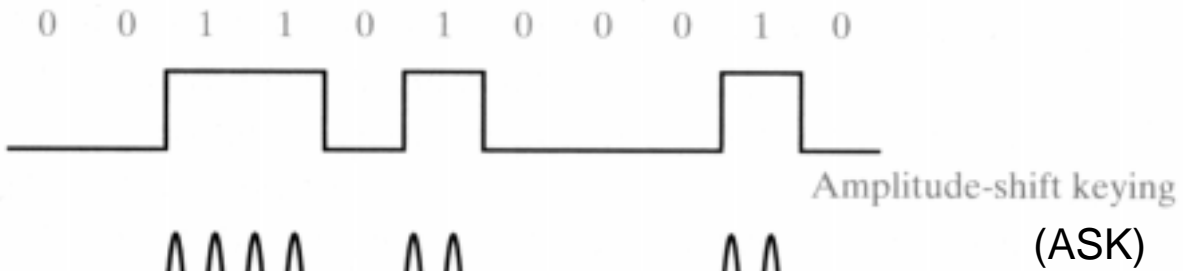
- ① A long string of 0's cause a problem in AMI  
A long string of 1's cause a problem in Pseudoternary

## 2. Digital Data ⇒ Analog Signals

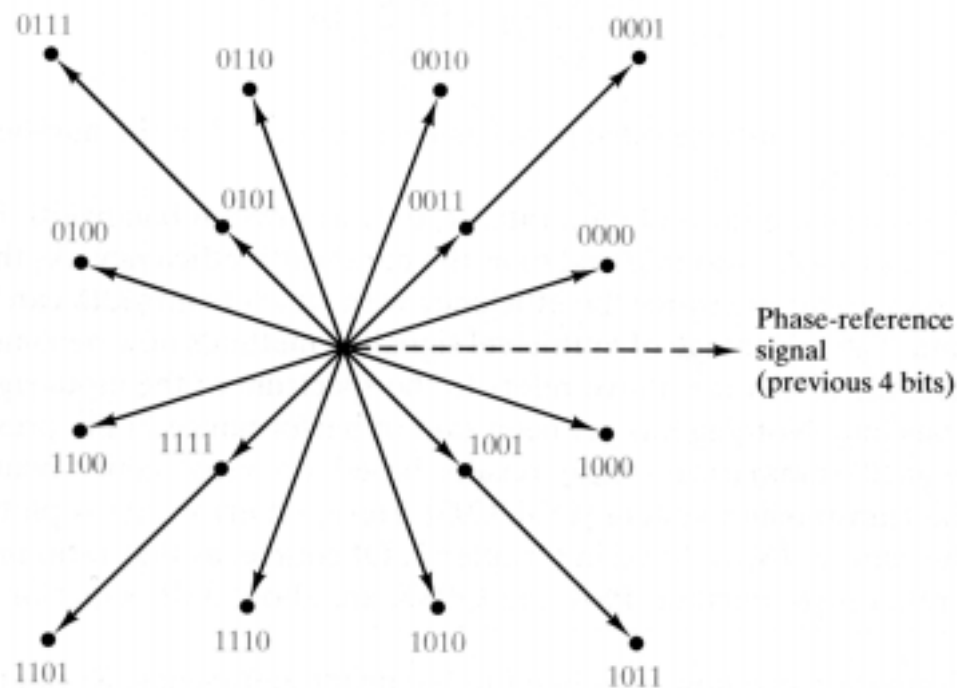
- Encoding is by modulation of a continuous sinusoidal carrier signal. This involves alteration of some characteristics of the carrier signal - amplitude, frequency, or phase.
- Various encoding techniques, ASK, FSK, PSK,...



	ASK	FSK	(Diff.) PSK
Binary 1	$A \cos(2\pi f_c t + \theta_c)$	$A \cos(2\pi f_1 t + \theta_c)$	$A \cos(2\pi f_c t + 180^\circ)$
Binary 0	0	$A \cos(2\pi f_2 t + \theta_c)$	$A \cos(2\pi f_c t)$



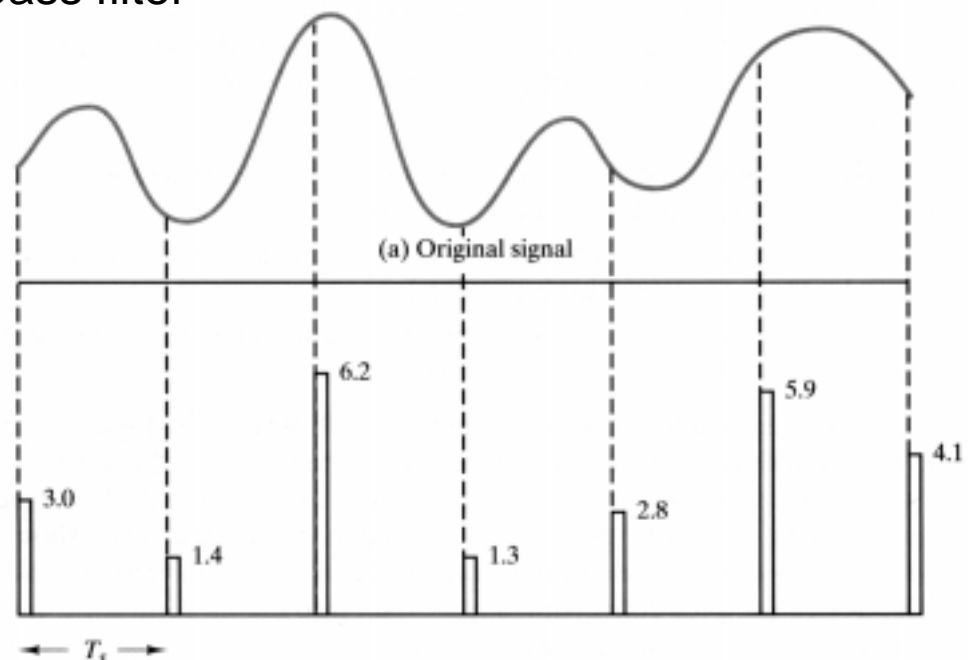
- QPSK(Quadrature PSK)
  - Each signal element represents two bits
    - Binary 11:  $\cos(2\pi f_c t + 45^\circ)$
    - Binary 10:  $\cos(2\pi f_c t + 135^\circ)$
    - Binary 00:  $\cos(2\pi f_c t + 225^\circ)$
    - Binary 01:  $\cos(2\pi f_c t + 315^\circ)$
- PSK using 12 angles and two amplitudes
  - 9,600 bps modem (2,400 baud x 4)



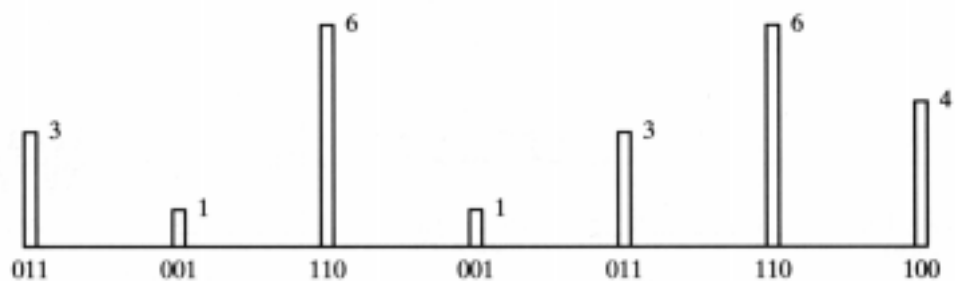
- Those patterns showing legal combinations of amplitude and phase are called **constellation patterns**
- 14,400 bps modem  $\Rightarrow$  64 points constellation pattern
- 28,800 bps modem  $\Rightarrow$  128 points

### 3. Analog Data $\Rightarrow$ Digital Signals

- PCM (Pulse Code Modulation)
  - Based on the **Nyquist's Sampling Theorem**: If a signal is periodically sampled at a rate  $\geq$  twice the highest significant frequency component in the signal, then it can be reconstructed from the samples by using a low-pass filter



(b) PAM pulses

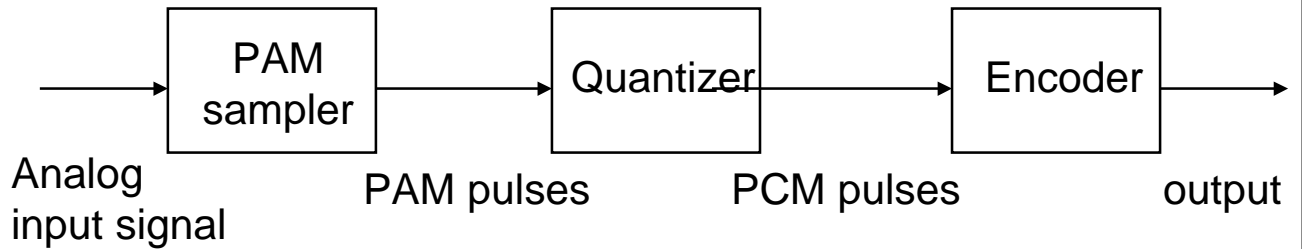


(c) PCM pulses

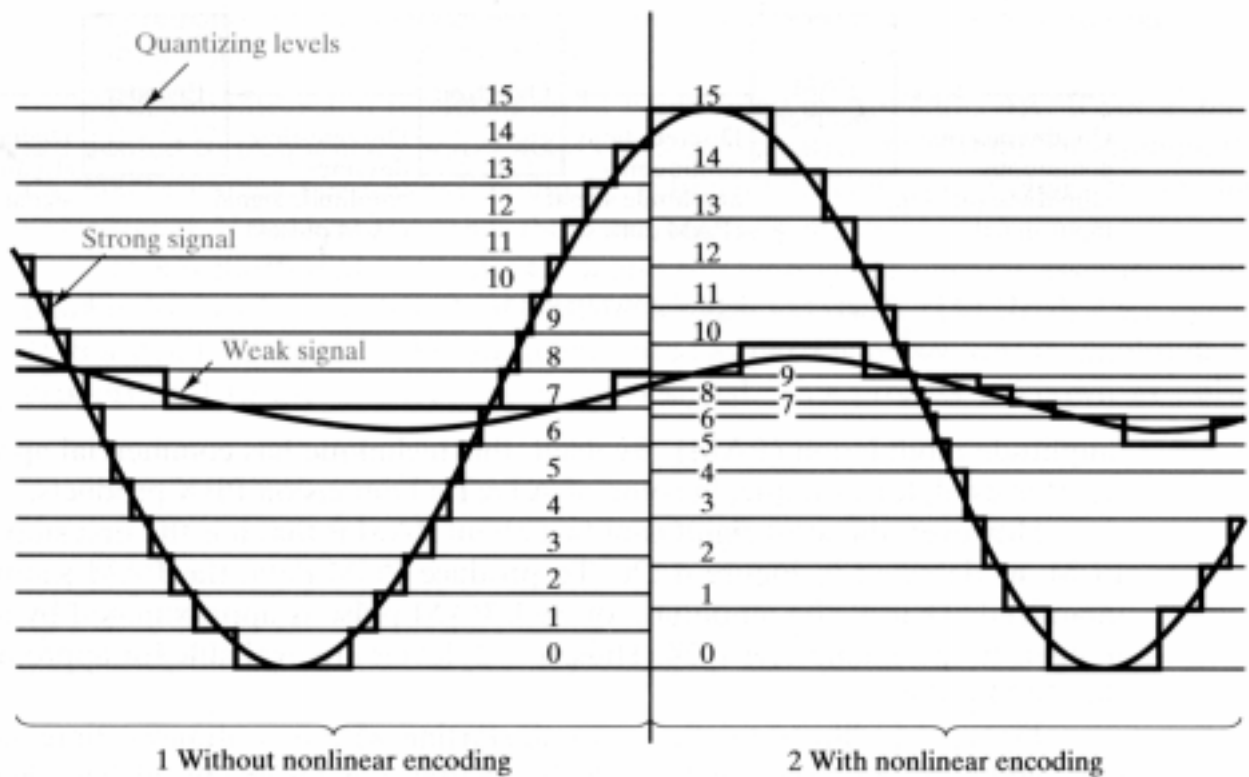
011001110001011110100

(d) PCM output

### Analog-to-digital conversion



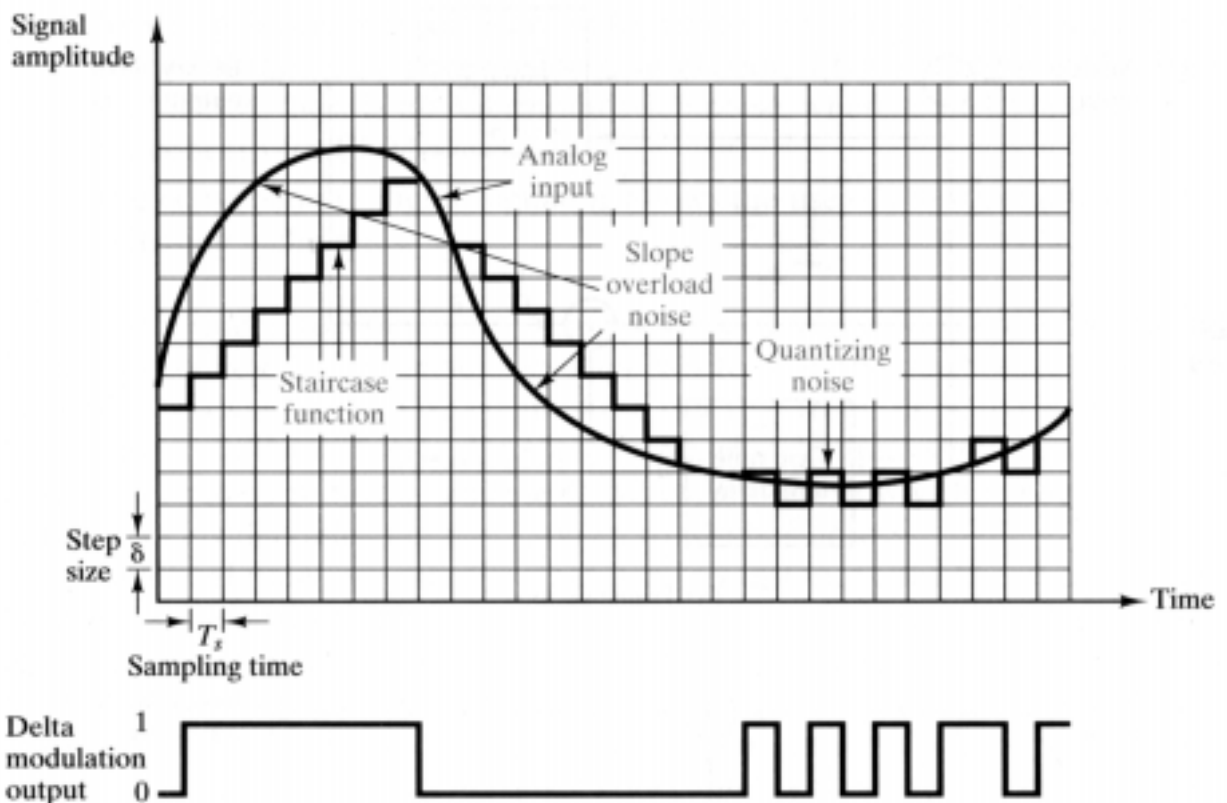
- Quantization noise:  $S/N = 6n + 1.8$  dB, where n is # of bits used
- To reduce quantization noise
  - large n or
    - Nonlinear coding
    - Companding

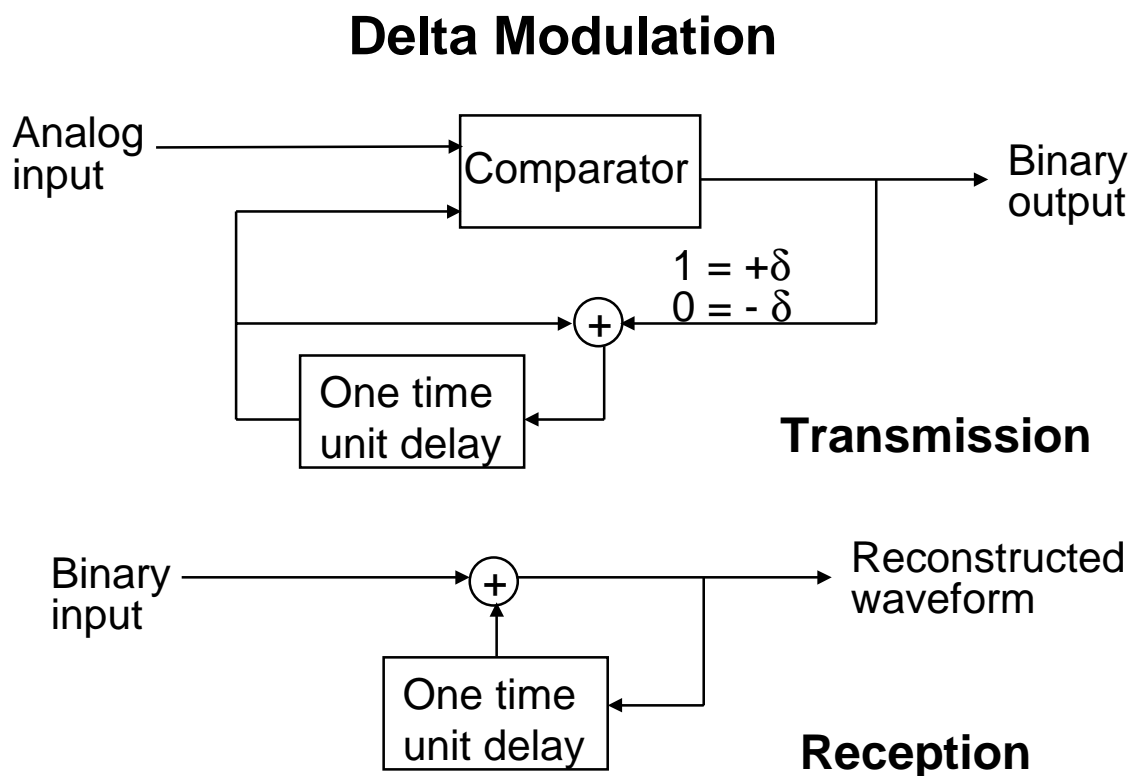


**Effect of nonlinear coding**

- DM (Delta Modulation)

- Uses “n” = 1, I.e., binary digital signal is produced; “0” stands for change of  $-\delta$  and “1” for change of  $+\delta$ .
- Higher sampling rate than PCM (Nyquist’s rate) is needed, but each sample uses only 1 bit instead of n.
- Implementation much simpler than PCM.





## 4. AnalogData $\Rightarrow$ Analog Signals

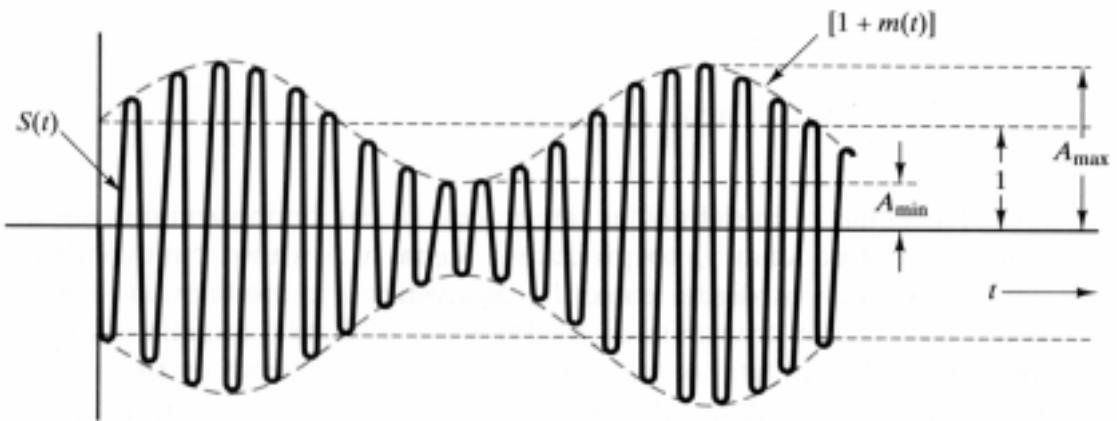
- Motivation
  - Low frequency analog signals cannot be transmitted on unguided media. (would require antennas with km diameters)  $\Rightarrow$  higher frequency needed.
  - For FDM (Frequency Division Multiplexing)

- AM (Amplitude Modulation)

$$s(t) = [1 + m(t)]\cos 2\pi f_c t$$

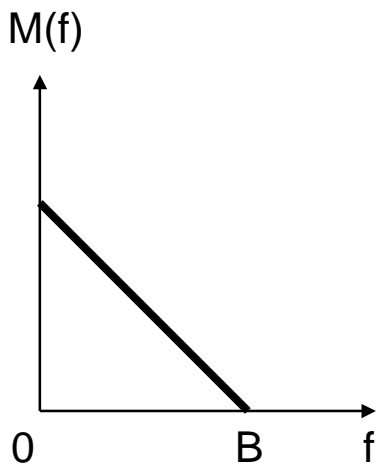


(a) Sinusoidal modulating wave

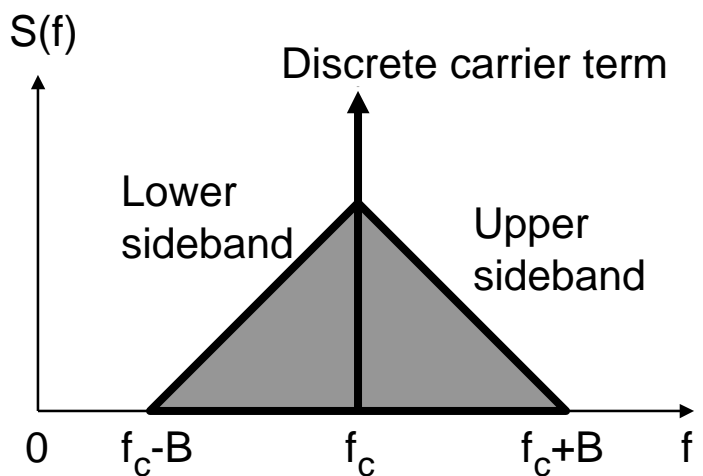


(b) Resulting AM signal

### Spectrum of an AM signal



Spectrum of modulating signal

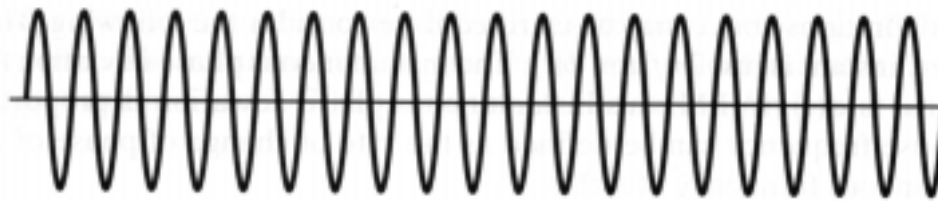


Spectrum of AM signal with carrier at  $f_c$  DSBTC

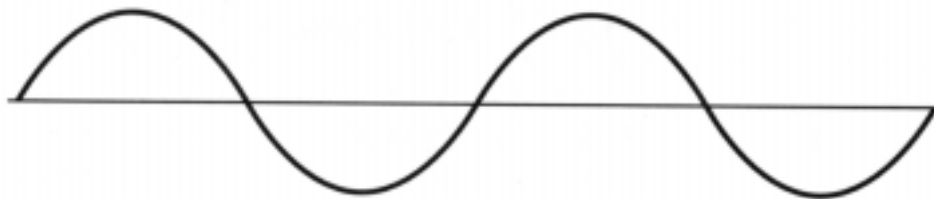
- Angle Modulation (FM and PM)

$$s(t) = A\cos[2f_c t + \phi(t)]$$

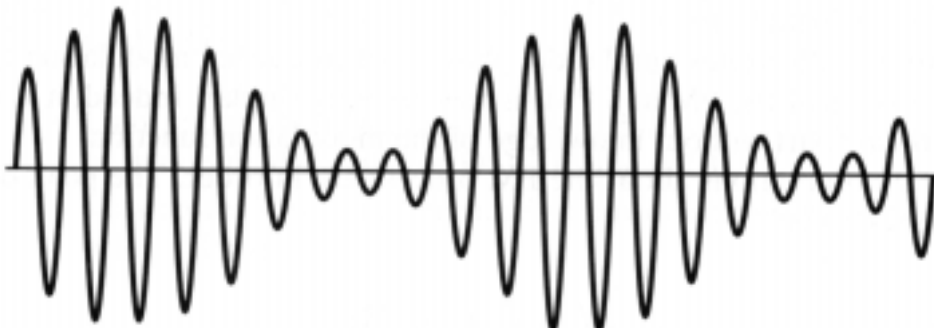
- PM:  $\phi(t) = n_p m(t)$
- FM:  $\phi'(t) = n_f m(t)$



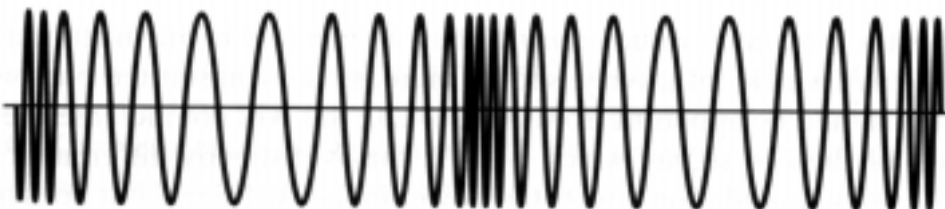
Carrier



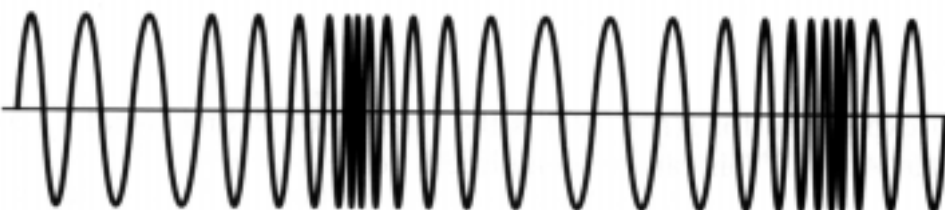
Modulating sine-wave signal



Amplitude-modulated (DSBTC) wave



Phase-modulated wave

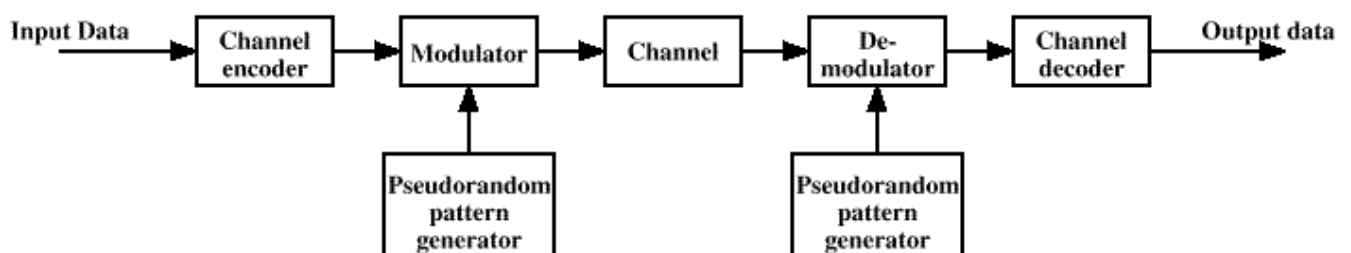


Frequency-modulated wave



## 5. Spread Spectrum

- Developed initially and popular for military and intelligence application
- Spread the info signal over a wider bandwidth in order to make jamming and interception more difficult

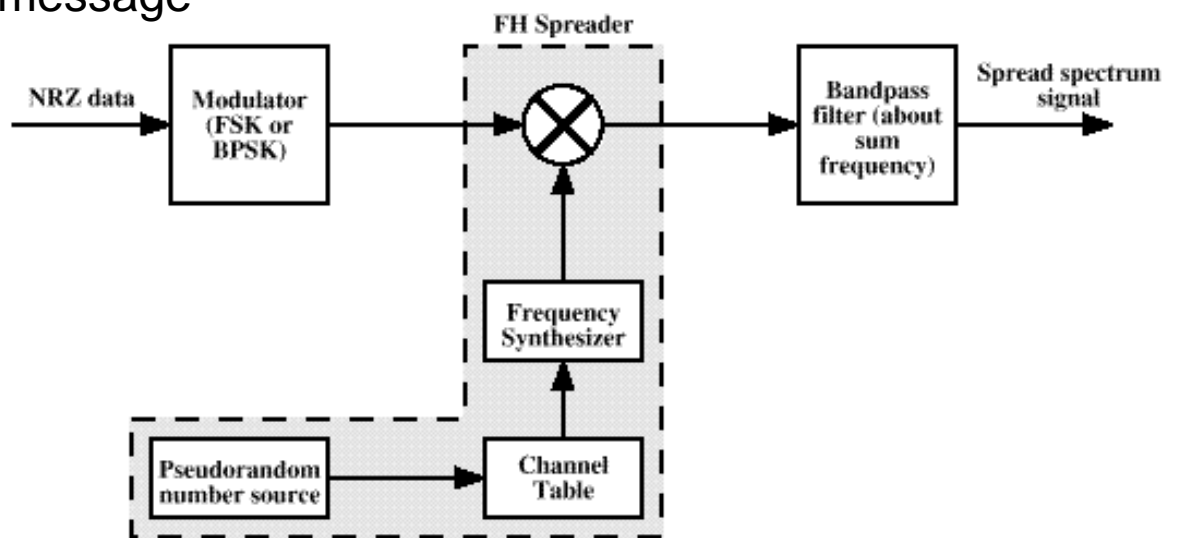


General model of spread spectrum digital communication system

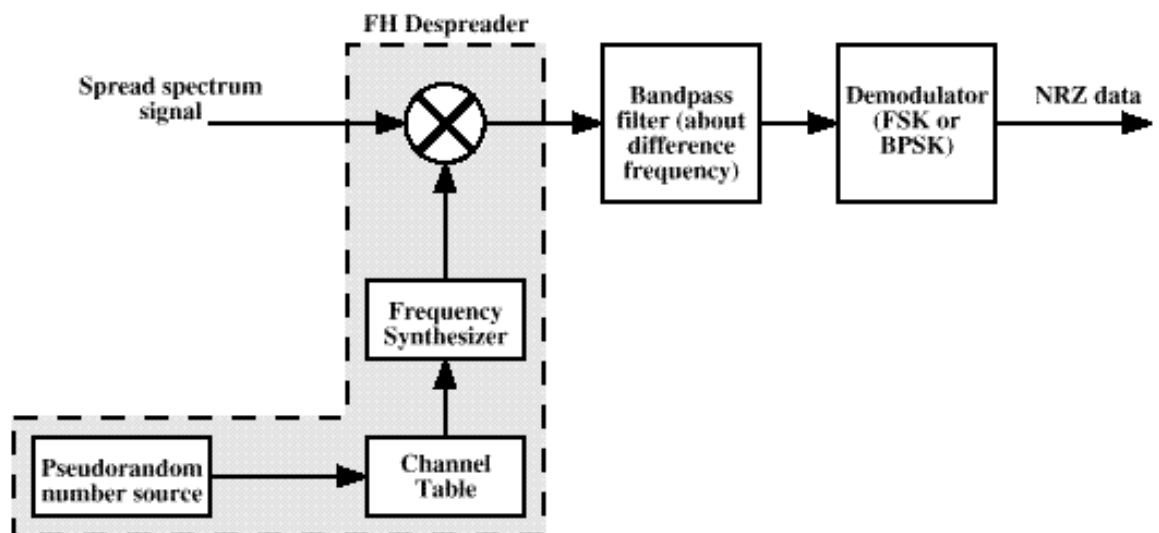
- Two types:
  - Frequency hopping and Direct sequence
- Basis for CDMA (Code Division Multiple Access)

- Frequency-Hopping

- Signal is transmitted over a seemingly random series of frequencies, hopping from frequency to frequency at split-second intervals.
- A receiver, hopping between frequencies in synchronization with the transmitter, picks up the message



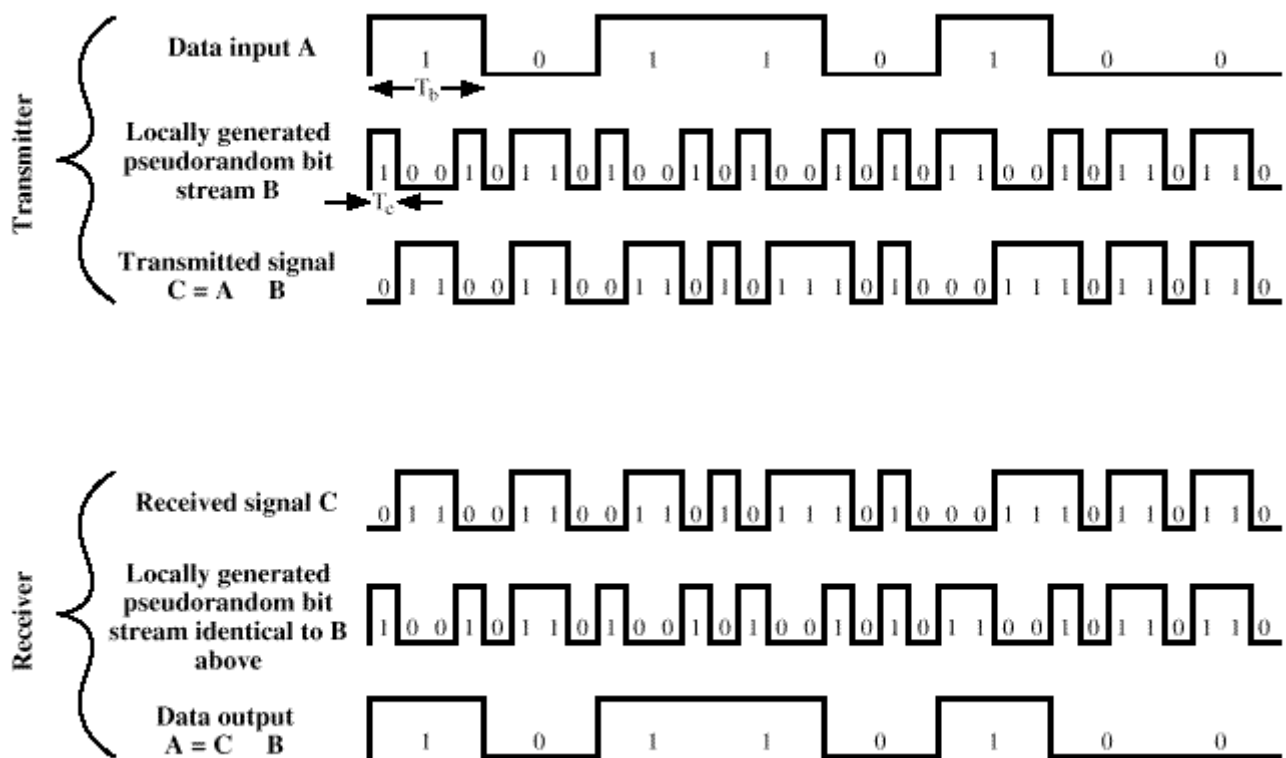
(a) Transmitter



(b) Receiver

• Direct Sequence

- Each bit in the original signal is represented by multiple bits (**chip code**) in the transmitted signal
- The chipping code spreads the signal across a wider frequency band in direct proportion to the number of bits used



**Example of direct sequence spread spectrum**